Regulator Design for Multidimensional Objects of the Second Order with Delay by Numerical Optimization

A.I. Ubert, V.G. Shachtshneider

Novosibirsk State Technical University, Novosibirsk, Russia

Abstract: Designing regulators for single-channel systems in the twenty-first century is no longer a difficult problem. Existing methods for their calculation by numerical optimization make it possible to relatively easily solve a substantial part of the problems, the solution of which was previously devoted to a lot of scientific articles, textbooks, monographs. Some of these tasks remained unsolved, which is associated with the specific features of the object models. Objects with many inputs and many outputs, called multichannel or multidimensional, and in the English language literature MIMO - Many Inputs Many Outputs - still pose a certain problem. Such problems are also solved in some cases by numerical optimization, but a systematic presentation of the methods for solving this problem is not enough in the literature. This article attempts to systematize the methodology for solving this problem with one example, which is of sufficient complexity due to the fact that in the matrix transfer function of the object, each element is a second-order link with a delay element. The application of the method of numerical optimization directly, without any preliminary analytical actions, did not lead to the desired result, therefore, some special methods were used, which are recommended for solving such problems.

Key words: mathematical modeling, regulators, controllers, PID, multichannel systems, MIMO, stability, accuracy, control in technical systems, automation, cybernetics, numerical simulation, optimization

REFERENCES

- [1] Zhmud V., Prokhorenko E., Liapidevskiy A. The design of the feedback systems by means of the modeling and optimization in the program VisSim 5.0/6. В сборнике: proceedings of the IASTED international conference on modelling, identification and control 30th IASTED conference on modelling, identification, and control, ASIAMIC 2010. Cep. "Proceedings of the 30th IASTED conference on Modelling, Identification, And Control, Asiamic 2010" Phuket, 2010. C. 27-32.
- [2] Zhmud V.A. Modeling, research and optimization of closed systems. Monograph / Novosibirsk State Technical University. Novosibirsk, 2012. (in Russian).
- [3] Zhmud V.A., Zavorin A.N. Metodi di ottimizzazione del controllo numerico su una modelli troncati. Italian Science Review. 2014. № 4 (13). C. 686-689.
- [4] Voevoda A.A., Zhmud V.A., Ishimtsev R.Y., Semibalamut V.M. The modeling tests of the new pidregulators structures. In: Proceedings of the IASTED International Conference on Applied Simulation and Modelling, ASM 2009 18th IASTED International Conference on Applied Simulation and Modelling, ASM 2009. Palma de Mallorca, 2009. C. 165-168.
- [5] Voevoda A.A., Zhmud V.A. Convergence of controller optimization algorithms for an object with a limiter and with a delay. Scientific Bulletin of the Novosibirsk State Technical University. 2007. No. 4 (29). S. 179-184. (in Russian).
- [6] Zhmud V., Yadrishnikov O., Poloshchuk A., Zavorin A. Modern key techologies in automatics: structures and numerical optimization of regulators. В сборнике: Proceedings 2012 7th International Forum on Strategic Technology, IFOST 2012 2012. C. 6357804.
- [7] Vasiliev V.A., Voevoda A.A., Zhmud V.A., Hassuoneh V.A. Digital controllers: target settings, selection of integration method, hardware implementation. Collection of scientific papers of Novosibirsk State Technical University. 2006. No. 4 (46). S. 3-10. (in Russian).

- [8] Zhmud VA, Yadryshnikov O. Numerical optimization of pid-regulators using the detector of the correctness of motion in the target function. Automation and software engineering. 2013. No. 1 (3). S. 24-29. (in Russian).
- [9] Zhmud V., Dimitrov L., Yadrishnikov O. Calculation of regulators for the problems of mechatronics by means of the numerical optimization method. В сборнике: 2014 12th International Conference on Actual Problems of Electronic Instrument Engineering APEIE 2014 Proceedings. 2014. C. 739-744.
- [10] Zhmud V., Vostrikov A., Semibalamut V. Feedback systems with pseudo local loops. В сборнике: Testing and Measurement: Techniques and Applications Proceedings of the 2015 International Conference on Testing and Measurement: Techniques and Applications, TMTA 2015 2015. C. 411-417.
- [11] Voevoda A.A., Zhmud V.A. Astatic control of objects with non-stationary matrix transfer functions by the method of approximate inversion of functional complex matrices. Scientific Bulletin of the Novosibirsk State Technical University. 2006. No. 2 (23). S. 3-8. (in Russian).
- [12] Zhmud V., Zavorin A. The design of the control system for object with delay and interval-given parameters. В сборнике: 2015 International Siberian Conference on Control and Communications, SIBCON 2015 Proceedings 2015. C. 7147060.
- [13] Zhmud V.A., Zavorin A.N. A method for designing energy-saving controllers for complex objects with a partially unknown model. In the collection: Problems of control and modeling in complex systems. Proceedings of the XVI International Conference. Institute for Management of Complex Systems, Samara Scientific Center of the Russian Academy of Sciences; Edited by: E.A. Fedosova, N.A. Kuznetsova, V.A. Wittich. 2014.S. 557-567. (in Russian).
- [14] Zhmud V.A., Goncharenko A.M. Modern problems of high-precision measurements of the phase differences.
 - В сборнике: Труды XIII Международной Научно-Технической Конференции Актуальные Проблемы Электронного Приборостроения. Proceedings: in 12 volumes. 2016. C. 314-318.

© Автоматика и программная инженерия. 2020, №2(32) http://www.jurnal.nips.ru

- [15] Zhmud V.A., Frantsuzova G.A., Vostrikov A.S. Dynamics of mechatronic systems. Textbook / Novosibirsk, 2014. (in Russian).
- [16] Zhmud V.A., Zavorin A.N. Model structure for optimizing a feedback system. Patent for invention RU 2554291 C1, 06.27.2015. Application No. 2014112628/28 of 04/01/2014. (in Russian).
- [17] Zhmud V.A., Zavorin A.N., Yadryshnikov O.D. Non-analytical methods for calculating PID controllers (in Russian). Textbook / Novosibirsk, 2013.

Alexey Igorevich Ubert - Senior Lecturer, Department of Automation, NSTU.

E-mail: ubert@corp.nstu.ru 630073, Novosibirsk, Ave. K. Marx, d.20

Vladimir Genrikhovich Shakhtschneider - Senior Lecturer, Department of Automation, NSTU. E-mail: sch@ait.cs.nstu.ru 630073, Novosibirsk, Ave. K. Marx, d.20

The paper has been received on 22/05/2020.